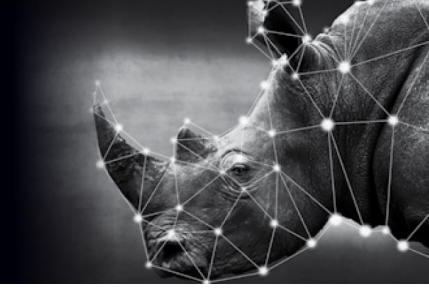


SESSION INFORMATION

In order to render the schedule of the Whova platform more visible, we provide a global view of programme and Question & Answer (Q&A) sessions schedule below:

- The first table provides the **tracks schedule** and **chairs** for the two Q&A sessions
- The second table complements with information on some **time zones** for the different blocks

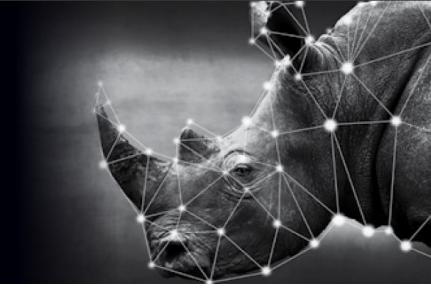
BLOCKS: Each day is divided into three session blocks: A, B, and C (see the *"Block #"* column in the schedule). The block number determines the time at which your session will run.

TRACKS: Each block accommodates 5 parallel tracks 1 – 5 that will run is different Zoom rooms (see the *"Track #"* column in the schedule).

Q&A SESSIONS: Each individual track will have two Q&A sessions. This is to account for attendees from different time zones. EAST Q&A will run earlier than WEST Q&A, so please check the time of your track in your corresponding time zone (see table Session Times).

TIME ZONES: For a summary of the session times, refer to the table Session Times. If your time zone is not in this table, you can also convert your session time using online tools like https://bit.ly/3g9Y7fv.

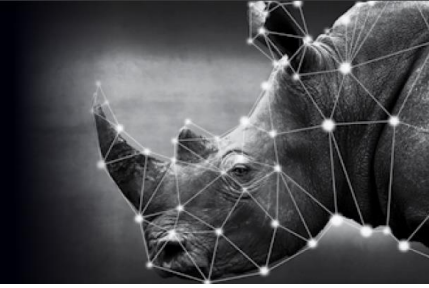
If you have any questions about the schedule feel free to contact us at program@fusion2020.org.



Session Schedule:

See the table "Session Times" for the schedule times.

Day	Block #	Track #	ID	Session Title	EAST Q&A Session Chair	WEST Q&A Session Chair
Tuesday, Jul 7		1	SS03-1	Advances in Distributed Kalman Filtering and Fusion 1	Benjamin Noack	Felix Govaers
		2	SS02	Data Fusion for Industry 4.0	Claudio De Farias	Jose Brancalion
		3	SS07	Context-based Information Fusion	Lauro Snidaro	Lauro Snidaro
		4	P21	Fusion for Image Data	Avishy Carmi	Benoit Debaque
	A	5	P22	Uncertain Reasoning	Jean Dezert	Lance Kaplan
		1	SS03-2	Advances in Distributed Kalman Filtering and Fusion 2	Felix Govaers	Susanne Radtke
		2	P01	Information Fusion for Energy Applications	Bharanidhar Duraisamy	Nageswara Rao
		3	P07	Registration	Ng Gee Wah	Chee-Yee Chong
		4	SS08-1	Machine Learning Methods 1 - Image Classification and Segmentation	Lyudmila Mihaylova	Pau Closas
	B	5	P11	Fusion for Social Systems	Valentina Dragos	Claire Laudy
		1	P18	Assignment Tracking	Ondrej Straka	David Crouse
		2	P02	Information Fusion for Automotive Applications	Simon Godsill	Ratnasingham Tharmarasa
		3	P19	Sensor Management	Martin Ulmke	Tilo Schwarz
		4	SS08-2	Machine Learning Methods 2 - Environmental Sensing	Simukai Utete	Simukai Utete
	C	5	SS10	Explainable AI for Information Fusion	Lauro Snidaro	Lauro Snidaro
Wednesday, Jul 8		1	P16	Multi-Bernoulli Filter	Zhansheng Duan	Chee-Yee Chong
		2	SS01-1	Evaluation of Techniques for Uncertainty Reasoning 1	Anne-Laure Jousselme	Paulo Costa
		3	SS05-1	Advanced Nonlinear Filtering 1 - Nonlinear Filtering	Ondrej Straka	Zheng Liu
		4	P04	Navigation	Molahlegi Molope	Molahlegi Molope
	A	5	SS04	Information Fusion in Multi-Biometrics and Forensics	Naser Damer	Raghavendra Ramachandra
		1	P14	Multiple Hypothesis Tracking	Murat Efe	Roy Streit
		2	SS01-2	Evaluation of Techniques for Uncertainty Reasoning 2	Valentina Dragos	Kathryn Laskey
		3	SS05-2	Advanced Nonlinear Filtering 2 - Filter Design	Víctor Elvira	Jordi Vilà-Valls
		4	SS08-3	Machine Learning Methods 3 - Forecasting	Lyudmila Mihaylova	Alta de Waal
	B	5	P03	Vehicle Localization	Alexander Charlish	Zhansheng Duan
		1	P17	Multi Model Tracking	Simon Godsill	Bharanidhar Duraisamy
		2	P23	Neural Networks	Alta DeWaal	Elisa Shahbazian
		3	P08	Variational Inference	Uwe Hanebeck	Zhansheng Duan
		4	SS08-4	Machine Learning Methods 4 - Wildlife Management	Allan de Freitas	Allan de Freitas
	C	5	P05	Indoor Localization	Fredrik Gustafsson	Pau Closas
Thursday, Jul 9		1	SS13	Extended Object and Group Tracking	Wolfgang Koch	Peter Willett
		2	SS05-3	Advanced Nonlinear Filtering 3 - Estimation	Jindřich Duník	Dale Blair
		3	P12	Maritime Applications	Anne-Laure Jousselme	Ranjeev Mittu
		4	P15	Random Finite Sets	Karl Granstroem	Yaakov Bar-Shalom
	A	5	SS06-1	Advances in Motion Estimation 1 - Inertial Sensors	Gustaf Hendeby	Gustaf Hendeby
		1	P13	Tracking Extended Objects	Le Yang	Avishy Carmi
		2	SS05-4	Advanced Nonlinear Filtering 4 - Nonlinear Tracking	Alexander Charlish	Darin Dunham
		3	P09	Fusion for Biomedical Applications	Gregov Pavlin	Sean O'Rourke
		4	P10	Fusion Using Semantic Information	Joachim Biermann	Elisa Shahbazian
	B	5	SS06-2	Advances in Motion Estimation 2 - Motion Analysis	Manon Kok	Manon Kok
		1	P20	Video Tracking	Ng Gee Wah	Terence van Zyl
		2	SS09	Directional Estimation	Uwe Hanebeck	Florian Pfaff
		3	SS11	Intelligence for Situation Understanding and Sensemaking	Kellyn Rein	Kellyn Rein
		4	P06	Outdoor Localization	Simon Godsill	Ting Yuan
	C	5		-- none --		



Session Times:

If your time zone is not in this table you can also convert your session time using online tools like: https://bit.ly/3g9Y7fv.

Time zone	EAST Q&A						WEST Q&A					
	Block A		Block B		Block C		Block A		Block B		Block C	
Australia East (UTC+10) *Example Sidney*	16:00:00	16:20:00	16:25:00	16:45:00	16:50:00	17:10:00	**3:00:00** ***Following day***	**3:20:00**	**3:25:00** ***Following day***	**3:45:00**	**3:50:00** ***Following day***	**4:10:00**
Asia (UTC+8) *Example Xi'an*	14:00:00	14:20:00	14:25:00	14:45:00	14:50:00	15:10:00	**1:00:00** ***Following day***	**1:20:00**	**1:25:00** ***Following day***	**1:45:00**	**1:50:00** ***Following day***	**2:10:00**
Europe/SA (UTC+2) *Example Paris*	8:00:00	8:20:00	8:25:00	8:45:00	8:50:00	9:10:00	19:00:00	19:20:00	19:25:00	19:45:00	19:50:00	20:10:00
UTC	6:00:00	6:20:00	6:25:00	6:45:00	6:50:00	7:10:00	17:00:00	17:20:00	17:25:00	17:45:00	17:50:00	18:10:00
North-America East (UTC-4) *Example Washington*	2:00:00	2:20:00	2:25:00	2:45:00	2:50:00	3:10:00	13:00:00	13:20:00	13:25:00	13:45:00	13:50:00	14:10:00
North-America West (UTC-7) *Example Seattle*	**23:00:00** ***Previous day***	**23:20:00**	**23:25:00** ***Previous day***	**23:45:00**	**23:50:00** ***Previous day***	0:10:00	10:00:00	10:20:00	10:25:00	10:45:00	10:50:00	11:10:00